



MDS-12-0110

COMPASS DEPTH METER & ALTIMETER MODULE

- Pressure range: 0 – 11 bar.
- Integrated 2D Compass.
- Integrated pressure sensor.
- Integrated 16 bits ADC.
- Integrated low power 8 bits MCU.
- 3-wire synchronous serial interface.
- Integrated software for pressure/depth/altitude calculation and compass.
- Internal EEPROM for calibration data storage
- Low power, low voltage.
- Integrated two Magnetic Sensors MF1_B.

Description

The MDS-12-0110 is a SMD module including a piezoresistive pressure sensor, an 8 bits MCU with integrated 16 bits ADC with interface for 2 high sensitivity compass magnetoresistive sensors. With its integrated firmware and calibrated pressure sensor, this device supplies to designer all processed information like temperature, water depth, atmospheric pressure, altitude, electronic compass heading and battery level. This high integration level allows an easy access to sensor technology without any background in it.

MDS-12-0110 is a low power, low voltage device that could be interfaced through its 3 wires synchronous interface to a low cost 4 bits MCU. An interface to a 2D MR sensors and its flipping circuit is also implemented.

Asynchronous interface is available on request.

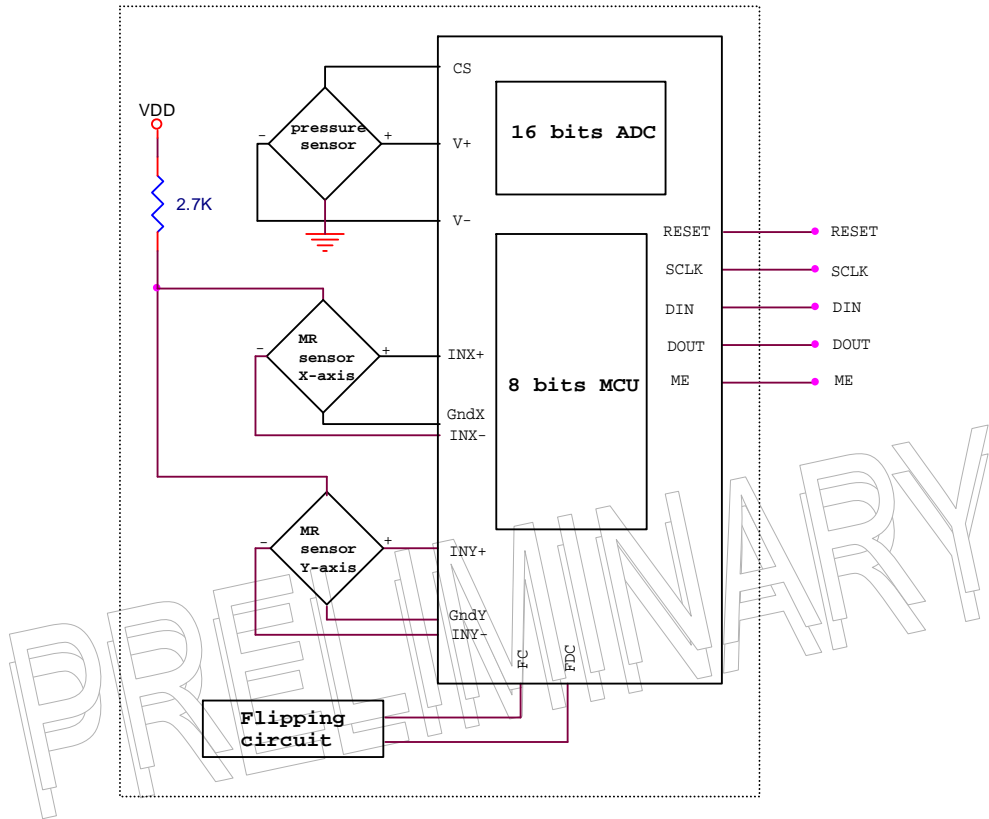
The small size of this module (10 x 10 x 6 mm) eases its integration in all watch applications.

Application

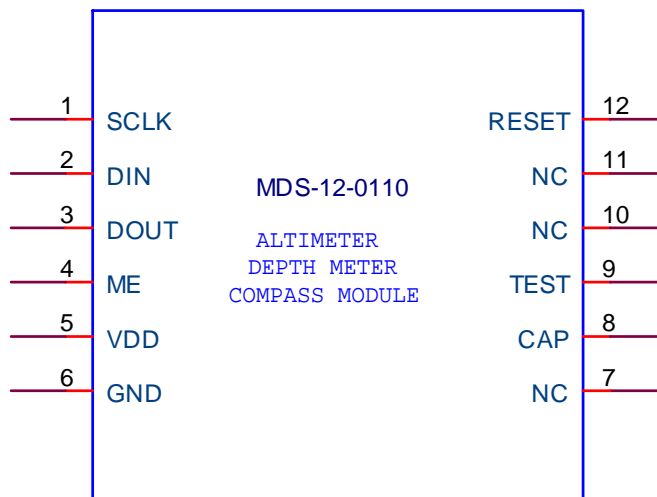
- 11 bar manometer . Res. up to 10mbar.
- Depth gauge or diving computer. Res. up to 0.1 m.
- Altimeter with resolution up to 1m or 3 ft
- Electronic compass with 1° resolution.
- High added-value sensor watches.



Block diagram



Pins description



Pinout of MDS-12-0110

Note:

1/ Pins 7, 10, 11 are for factory use. Must be left open.



Pin name	Pin no	Description	Sleep mode	Stand by mode	Active mode
SCLK	1	Synchronous serial interface clock	Output Low	Output Low	Input Data
DIN	2	Data in of synchronous serial interface	Output Low	Output Low	Input Data
DOUT	3	Data out of synchronous serial interface	Output Low	Output Low	Output Data
ME	4	Module enable – Wake up the module from standby mode	Input pull high	Input pull high	Input pull high
VDD	5	Positive power supply	VDD	VDD	VDD
GND	6	Negative power supply	GND	GND	GND
CAP	8	External capacitor for flipping circuit	X	X	X
TEST	9	Production test pin. Connect to VDD	VDD	VDD	VDD
RESET	12	Reset pin	GND	GND	Pulse High

Absolute maximum ratings

Description	Value
Maximum voltage applied between any pin (but TEST VDD) and GND	5.5V
Voltage applied to any pin (but TEST VDD)	GND - 0.3V to VDD + 0.3V
Maximum storage temperature	85°C
Proof pressure	20 bars
Burst pressure	35 bars



Normal operating conditions

Parameter	Symbol	Conditions	Min	Typical	Max	Unit
Power supply	V_{DD}		2.4	3.0	3.3	V
Supply current		$V_{DD} = 3V$ 1 reading per second				
Average in temperature mode	I_{avgT}		(*)	24	(*)	μA
Average in pressure mode	I_{avgP}		(*)	34	(*)	μA
Average in altitude/depth mode	I_{avgA}		(*)	38	(*)	μA
Average in compass mode	I_{avgC}		(*)	35	(*)	μA
Powerdown in standby mode	I_{stb}			2	6	μA
Powerdown in sleep mode	I_{slp}			1	3	μA
Operating pressure range	P		0		11	bar
Operating temperature range	T_a		-10		+60	$^{\circ}C$
Operating depth range	D		0		100	m
Operating altitude range	A		-700		+9000	m
Synchronous serial clock	Sclk			32.768	70.000	KHz
Voltage level detector	Vld		2.4-10%	2.4	2.4+10%	V

Note: (*) not yet defined

Pressure and temperature output characteristics

Parameter	Symbol	Test conditions	Min	Typ.	Max	Unit	Note
Resolution				0.5		mbar	
Absolute pressure accuracy		P = 0 ... 10 bar T=30 $^{\circ}C$	-10.0		+10.0	mbar	1
Relative pressure accuracy		P = 0 ... 10 bar	-5		+5	mbar	2
Maximum pressure error over temperature		$T_a = 0 \dots +50^{\circ}C$	-15		+15	mbar	3
Long-term stability		one year					
Maximum error over supply voltage		VDD = 2.7V ... 3.3V	-10		+10	mbar	4
Temperature accuracy		T= -10 $^{\circ}C$... + 60 $^{\circ}C$	-1		+1	$^{\circ}C$	5

Notes :

- 1/ Maximum error of pressure reading over the pressure range.
- 2/ Maximum error of pressure reading at one pressure point.
- 3/ Maximum error of pressure reading over the temperature range.
- 4/ Maximum error of pressure reading / temperature reading over supply voltage range.
- 5/ Maximum error of temperature reading over the temperature range.



Compass output characteristics

Parameter	Symbol	Conditions	Min	Typ	Max	Unit	Note
Resolution		VDD = 3V		1		°	
Heading accuracy		VDD = 3V	-3		+3	°	

Notes : The accuracy is defined by rotating the compass on horizontal plane on the 360° degree gabarit.

Serial communication commands

- The module will enter standby mode after power on reset, reset by RESET pin or executing a command. The reset duration is 100ms.
- The reset of MDS will be active when the RESET pin goes to HIGH. When the RESET pin goes to LOW the MDS will enter reset cycle. After releasing reset cycle, all calibrated data will be reloaded from the internal EEPROM and the MDS will then enter standby mode after 100ms.
- For each byte, MSB is sent first and LSB at the end.
- The data is in hexadecimal format. **Negative number is in 2's complement.**
- When the module enters Sleep Mode, all calibration data will be saved in EEPROM. This mode can be used to reduce current consumption when the host MCU stops reading MDS for a long time. In this mode the oscillator is stopped.
- To wake up the module from sleep mode, the host MCU must pull HIGH the Reset pin for at least 10ms. The module will start and enter standby mode within 100ms after Reset pin goes to LOW level. Then, the host MCU can send a new command.
- The maximum delay between active low of ME pin and active high of DOUT pin is 4ms.

The information supplied by the MDS-12-0110 module could be sent to the host MCU on request. Hereunder, the list of commands issued by the host MCU to the compass altimeter module.

Commands name	Note	Code	Host MCU	MDS-12-0110
TEMP in deg C	1	44h	Send 1 byte code	Send 2 bytes temp data
TEMP in deg F	2	5Fh	Send 1 byte code	Send 2 bytes temp data
PRESSURE in mbar	3	45h	Send 1 byte code	Send 4 bytes pressure data
PRESSURE in inHg	4	5Ch	Send 1 byte code	Send 4 bytes pressure data
PRESSURE in psi	5	5Eh	Send 1 byte code	Send 4 bytes altitude data
ALTITUDE in m	6	48h	Send 1 byte code	Send 4 bytes altitude data
ALTITUDE in ft	7	5Dh	Send 1 byte code	Send 4 bytes altitude data
STORE PRESSURE WITH OFFSET in mbar	8	4Eh	Send 1 byte code and after receiving 4 bytes pressure data, will send 4 bytes pressure data (mbar) with offset	Send 4 bytes pressure data in mbar
STORE PRESSURE WITH OFFSET in inHg	9	55h	Send 1 byte code and after receiving 4 bytes pressure data, will send 4 bytes pressure data (inHg) with offset	Send 4 bytes pressure data in inHg



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STORE PRESSURE WITH OFFSET in PSI	10	56h	Send 1 byte code and after receiving 4 bytes pressure data, will send 4 bytes pressure data (PSI) with offset	Send 4 bytes pressure data in PSI
STORE TEMPERATURE WITH OFFSET in deg C	11	4Dh	Send 1 byte code and after receiving and 2 bytes temperature data, will send 2 bytes temperature data (deg C) with offset	Send 2 bytes temperature data in deg C
STORE TEMPERATURE WITH OFFSET in deg F	12	54h	Send 1 byte code and after receiving and 2 bytes temperature data, will send 2 bytes temperature data (deg F) with offset	Send 2 bytes temperature data in deg F
AZIMUTH 2D	13	4Ch	Send 1 byte code	Send 2 bytes data
COMPASS USER CALIBRATION	14			
Start calibration		4Ah	Send 1 byte code	Send 2 bytes data 004Ah
Calibration		4Bh	Send 1 byte code	Send 2 bytes data 004Bh
End calibration		49h	Send 1 byte code	Send 2 bytes data 0049h
VOLTAGE LEVEL DETECTOR	15	5Ah	Send 1 byte code	Send 2 bytes data 00h or F4h
SLEEP MODE	16	43h	Send 1 byte code and after send 2 bytes data 66h 77h	Go to sleep mode
COMMUNICATION TEST	17	40h	Send 1 byte code and 4 bytes data	Send 4 bytes data
STORE SEA LEVEL PRESSURE in mbar	18	47h	Send 1 byte code and 4 bytes data	
STORE SEA LEVEL PRESSURE in inHg	19	57h	Send 1 byte code and 4 bytes data	
STORE SEA LEVEL PRESSURE in PSI	20	5Bh	Send 1 byte code and 4 bytes data	
DEPTH IN METER/SEA	21	71h	Send 1 byte code 71h	Send 4 bytes depth in meter
DEPTH IN FEET/SEA	22	72h	Send 1 byte code 72h	Send 4 bytes depth in feet
DEPTH IN METER/LAKE	23	76h	Send 1 byte code 76h	Send 4 bytes depth in meter
DEPTH IN FEET/LAKE	24	77h	Send 1 byte code 77h	Send 4 bytes depth in feet
SET DEPTH 0M	25	73h	Send 1 byte code 73h	Send 2 bytes 0073h
DEPTH PRESSURE in mbar	26	74h	Send 1 byte code 74h	Send 4 bytes depth pressure in mbar

Notes:

1. **Read Temperature in deg C:** the Host MCU sends 1 byte code, and then receives 2 bytes data of temperature from the MDS module. To get the correct temperature, temperature data must be divided by 10. Temperature range from -10°C to 60°C and res 0.1°C.
2. **Read Temperature in deg F:** the Host MCU sends 1 byte code, and then receives 2 bytes data of temperature from the MDS module. To get the correct temperature, temperature data must be divided by 10. Temperature range from 14°F to 140°F and res 0.1°F.



3. **Read Pressure in mbar:** the Host MCU sends 1 byte code, and then receives 4 bytes data of pressure the MDS module. Pressure data must be divided by 100 to get the actual pressure. Pressure range is from 300.0 mbar to 1100.0 mbar res 0.1 mbar.
4. **Read Pressure in inHg:** the Host MCU sends 1 byte code, and then receives 4 bytes data of pressure the MDS module. Pressure data must be divided by 10000 to get the actual pressure. Pressure range is from 8.8472 inHg to 32.4400 inHg res 0.0001 inHg.
5. **Read Pressure in PSI:** the Host MCU sends 1 byte code, and then receives 4 bytes data of pressure the MDS module. Pressure data must be divided by 10000 to get the actual pressure. Pressure range is from 4.3511 PSI to 15.9543 psi res 0.0001 PSI.
6. **Read Altitude in m:** the Host MCU sends 1 byte code and then receives 4 bytes data of altitude from the MDS module. To get the correct altitude in m, data must be divided by 10.
7. **Read Altitude in ft:** the Host MCU sends 1 byte code and then receives 4 bytes data of altitude from the MDS module. The received data is the correct data.
8. **Calculate and store pressure with offset in mbar:** the Host MCU sends 1 byte code, waits for 4 bytes pressure data (without offset) from the MDS module and then the Host MCU will send 4 bytes of corrected pressure data (pressure data with offset). Before, the corrected pressure data must be multiplied by 100.
To reset the pressure offset stored in MDS module, the host MCU must re-send 4 bytes pressure data (without offset) that just received from MDS module to MDS module.
9. **Calculate and store pressure with offset in inHg:** the Host MCU sends 1 byte code, waits for 4 bytes pressure data (without offset) from the MDS module and then the Host MCU will send 4 bytes of corrected pressure data (pressure data with offset). Before, the corrected pressure data must be multiplied by 10000.
To reset the pressure offset stored in MDS module, the host MCU must re-send 4 bytes pressure data (without offset) that just received from MDS module to MDS module.
10. **Calculate and store pressure with offset in PSI:** the Host MCU sends 1 byte code, waits for 4 bytes pressure data (without offset) from the MDS module and then the Host MCU will send 4 bytes of corrected pressure data (pressure data with offset). Before, the corrected pressure data must be multiplied by 10000.
To reset the pressure offset stored in MDS module, the host MCU must re-send 4 bytes pressure data (without offset) that just received from MDS module to MDS module.
11. **Calculate and store temperature offset in deg C:** the Host MCU sends 1 byte code, waits for 2 bytes temperature data from the MDS module and then the Host MCU will send 2 bytes of corrected temperature data (temperature data with offset). Before, the corrected temperature data must be multiplied by 10.
To reset the temperature offset stored in MDS module, the host MCU must re-send 2 bytes temperature data (without offset) that just received from MDS module to MDS module.
12. **Calculate and store temperature offset in deg F:** the Host MCU sends 1 byte code, waits for 2 bytes temperature data from the MDS module and then the Host MCU will send 2 bytes of corrected temperature data (temperature data with offset). Before, the corrected temperature data must be multiplied by 10.
To reset the temperature offset stored in MDS module, the host MCU must re-send 2 bytes temperature data (without offset) that just received from MDS module to MDS module.
13. **Read Azimuth 2D compass:** the Host MCU sends 1 byte code and then receives 2 bytes data from MDS-12-0110 module. At 2 bytes data: 12 bits LSB for azimuth (AZI), 3 bits LSB of 4 bits MSB for cardinal and semicardinal points (CP), and 1 bit MSB for error due to strong magnetic field (Err).

- AZI : 0°...359°
- CP = 0 : North
- CP = 1 : North - East
- CP = 2 : East
- CP = 3 : South - East
- CP = 4 : South
- CP = 5 : South - West
- CP = 6 : West



- CP = 7 : North - West
- Err = 0 : normal magnetic field.
- Err = 1 : error strong magnetic field.

There will be error if the read values of MR sensors are 20% more than the maximum values or 20% less than the minimum values. Maximum and minimum values are those got during calibration. There will be error also if the compass is not calibrated.

14. **User calibration for compass** : the Host MCU must follow this order of commands : START calib, CALIB and END calib. START command is sent once at start calibration and END command once at the end of calibration, CALIB command must be sent continuously (i.e. every 1s) during calibration and the compass must be turned very slowly at horizontal level for at least 360°. Each time, CALIB Code is sent by the MCU, the module will acknowledge the Host MCU order by returning 2 bytes data (4Bh). If CR2032 battery is used, it is recommended that the host MCU sends in maximum 4 CALIB command (4Bh) per second.

After the Host MCU sends 1 byte code then the Host MCU will receive 2 bytes data from the module.

15. **Voltage level detector** : the Host MCU sends 1 byte code and then receives 2 bytes data. If the power supply voltage is less than 2.44V then the module will be returned F4h, and if the power supply voltage is more than 2.44V then the module will be returned 00h. The absolute precision of the detection voltage level is $\pm 10\%$. The maximum duration of measurement is 4ms. After measurement, the module will send 2 bytes data and return to standby mode.
16. **Sleep mode** : the Host MCU sends 1 byte code and then continuously 2 bytes data 66h and 77h to ask the module to enter sleep mode.
17. **Communication test** : the Host MCU sends 1 byte code and 4 bytes data. The module gets the 4 bytes data and returns them to the Host MCU. Then, this latter can check that the communication is correct.
18. **Store sea level pressure in mbar**: the Host MCU sends 1 byte code and 4 bytes data. The module gets the 4 bytes data new pressure at sea level. The default pressure at sea level is 1013.25 mbar.
19. **Store sea level pressure in inHg**: the Host MCU sends 1 byte code and 4 bytes data. The module gets the 4 bytes data new pressure at sea level.
20. **Store sea level pressure in PSI**: the Host MCU sends 1 byte code and 4 bytes data. The module gets the 4 bytes data new pressure at sea level.
21. **Read depth in m for sea water**: the Host MCU sends 1 byte code and then receives 4 bytes data of depth from the MDS module. To get the correct depth in m, data must be divided by 10.
22. **Read Depth in ft for sea water**: the Host MCU sends 1 byte code and then receives 4 bytes data of depth from the MDS module. The received data is the correct data.
23. **Read depth in m for lake water**: the Host MCU sends 1 byte code and then receives 4 bytes data of depth from the MDS module. To get the correct depth in m, data must be divided by 10.
24. **Read depth in m for lake water**: the Host MCU sends 1 byte code and then receives 4 bytes data of depth from the MDS module. To get the correct depth in m, data must be divided by 10.
25. **Set 0m depth**: the Host MCU sends 1 byte code and then receives 2 bytes data from the MDS module for confirmation.
26. **Read depth pressure in mbar**: the Host MCU sends 1 byte code and then receives 4 bytes data of depth pressure in mbar from the MDS module.



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Note: when communicating with MDS module, if the Host MCU writes code or writes data to MDS module, the MDS module will receive data at the rising edge of SCLK. If the Host MCU receives the data from MDS module the Host MCU should receive data at the falling edge of SCLK.

Please see the below table for the detail of data sending by MDS module:

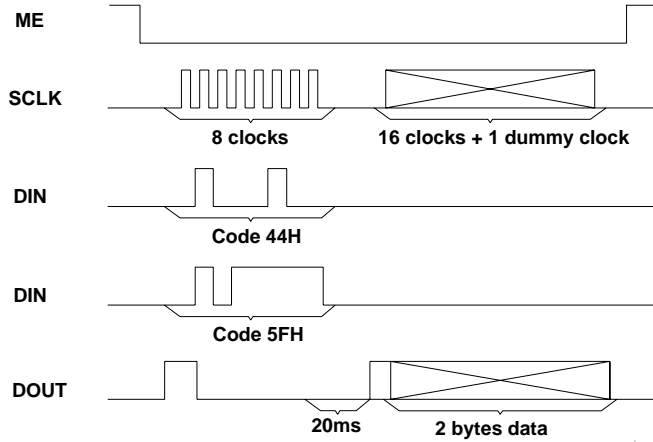
Item	Description	Unit	MDS's data	Real data
1	Temperature data	°C/°F	00FFh	25.5
2	Temperature data	°C/°F	FF9Ch	-10.0
3	Altitude/Depth data	m	00000FFh	25.5
4	Altitude/Depth data	m	FFFFFF9Ch	-10.0
5	Altitude/Depth data	ft	00000FFh	255
6	Altitude/Depth data	ft	FFFFFF9Ch	-100
7	Pressure data	mbar	000186A0h	1000.00
8	Pressure data	inHg	00048828h	29.7000
9	Pressure data	PSI	00023668h	14.5000

PRELIMINARY

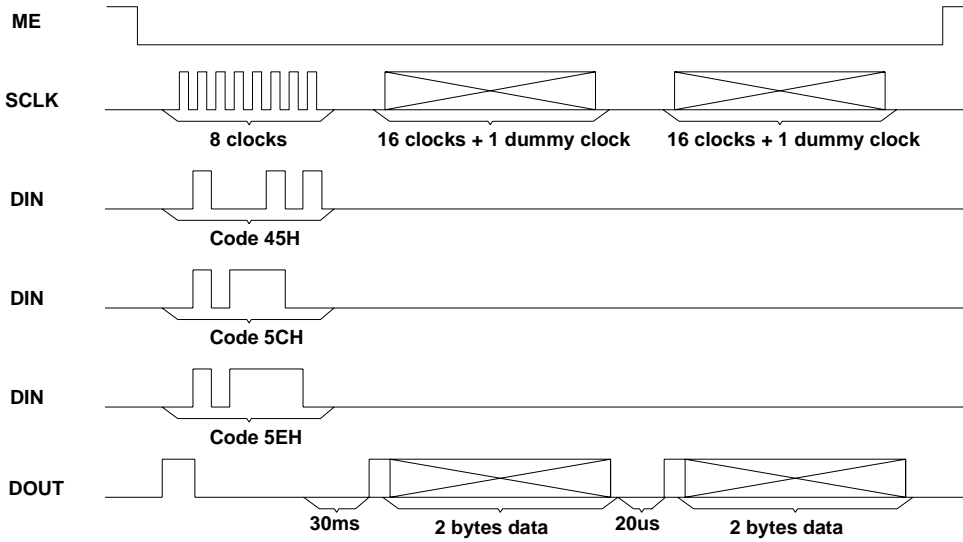


Timing diagrams

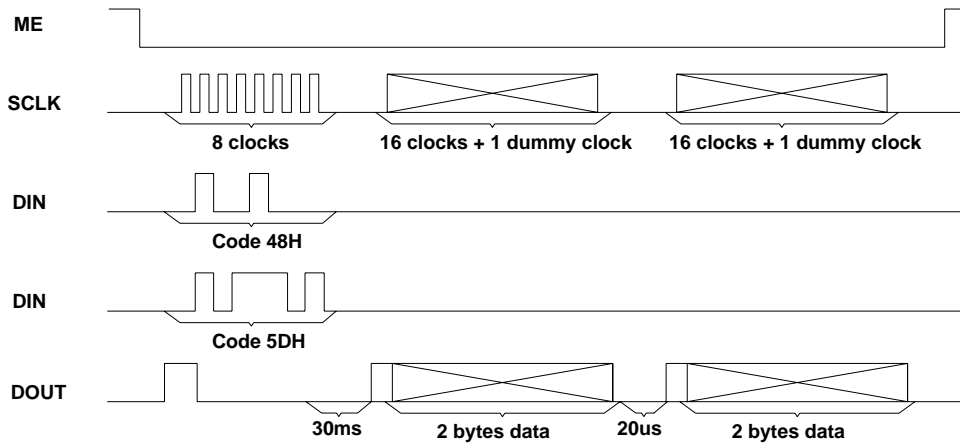
TEMPERATURE



PRESSURE

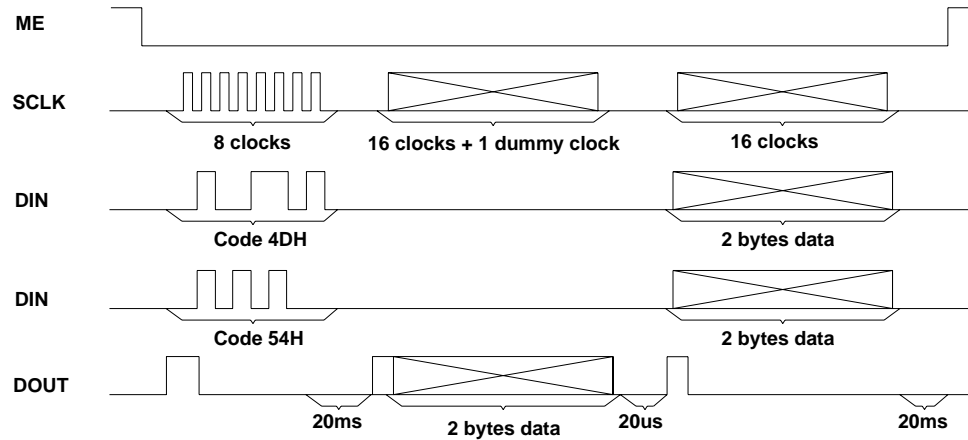


ALTITUDE

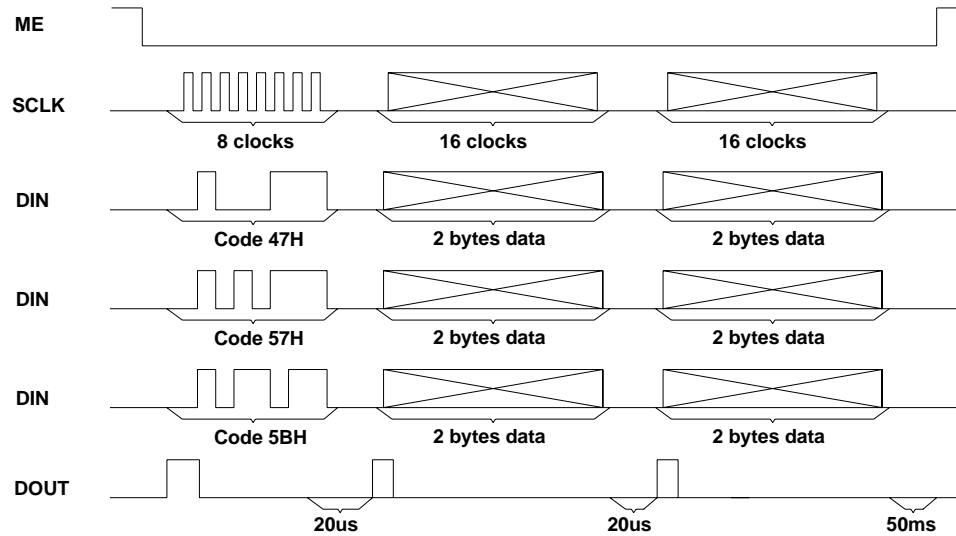




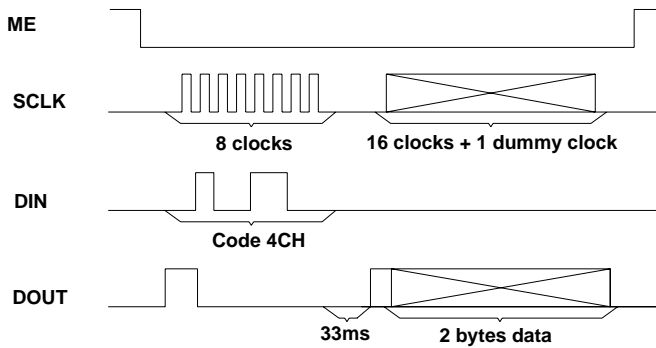
STORE TEMPERATURE WITH OFFSET



STORE PRESSURE SEA LEVEL

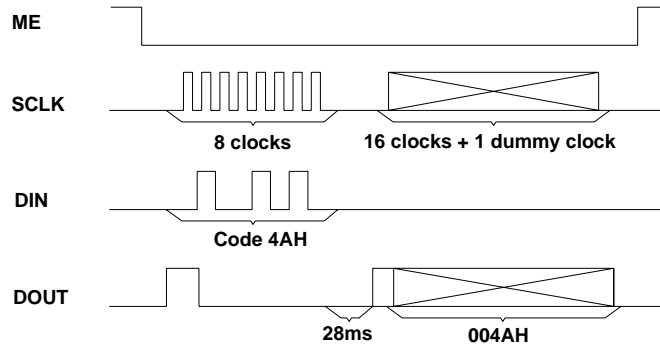


AZIMUTH 2D

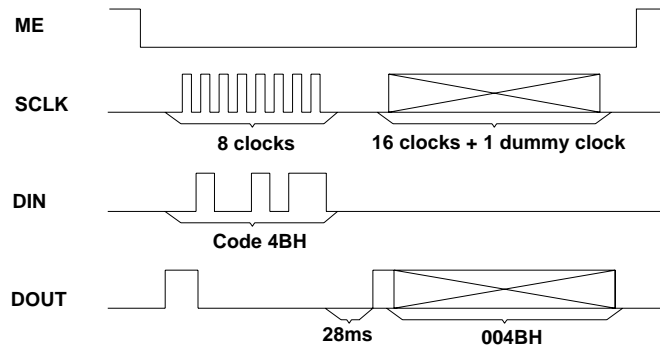




START CALIBRATION

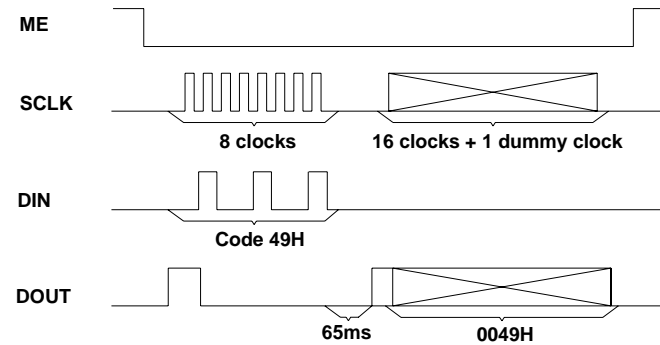


CALIBRATION

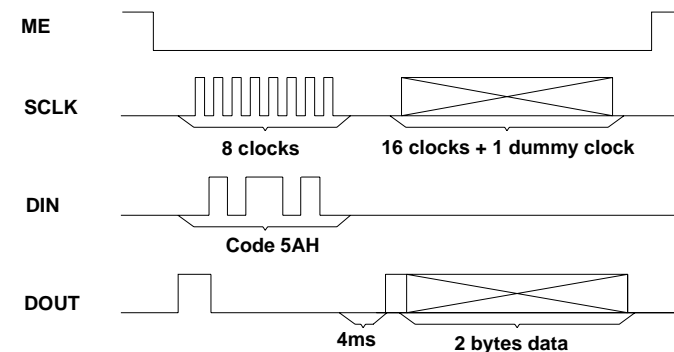


BINARY

STOP CALIBRATION

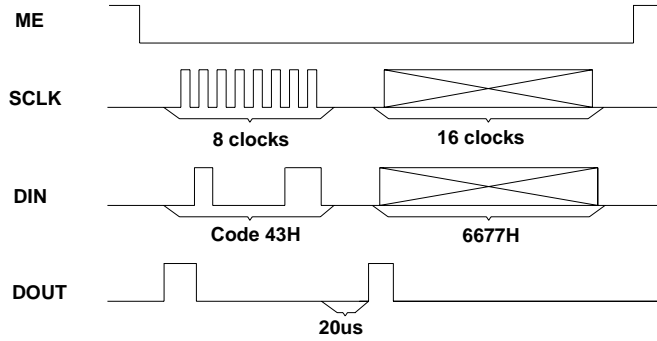


VOLTAGE LEVEL DETECTOR

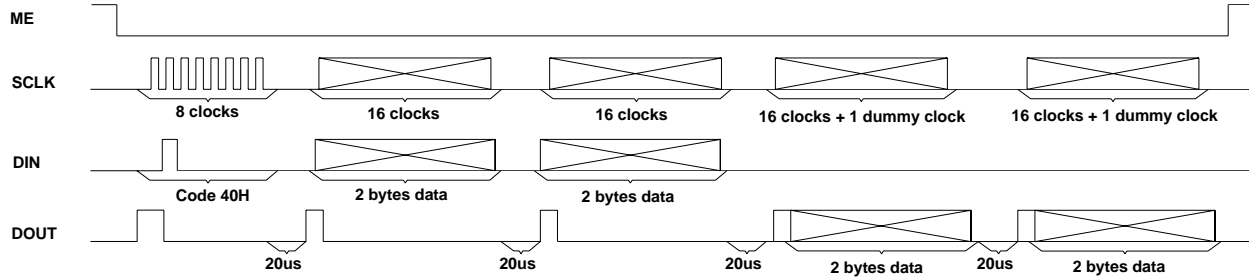




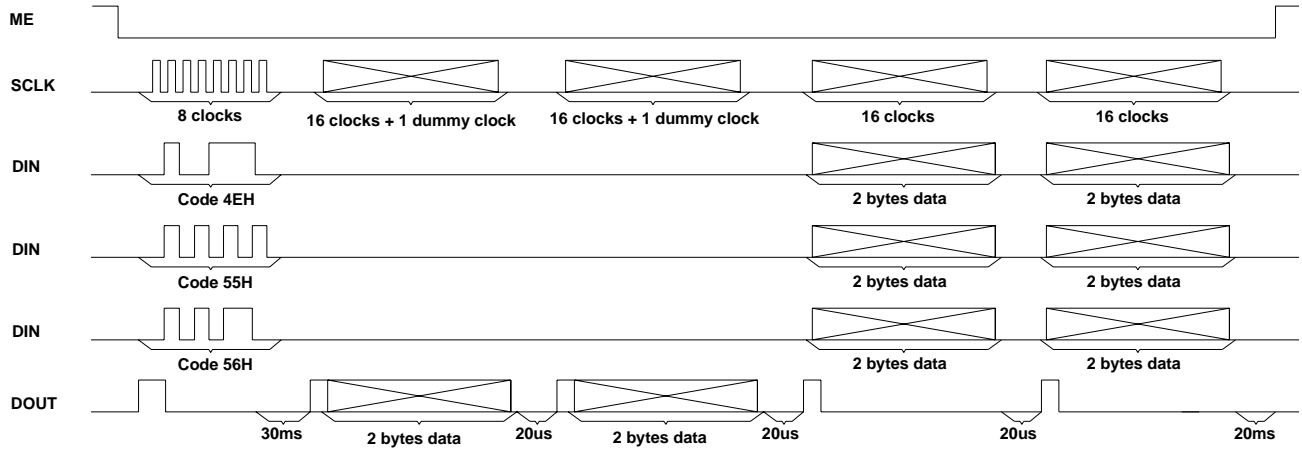
SLEEP MODE



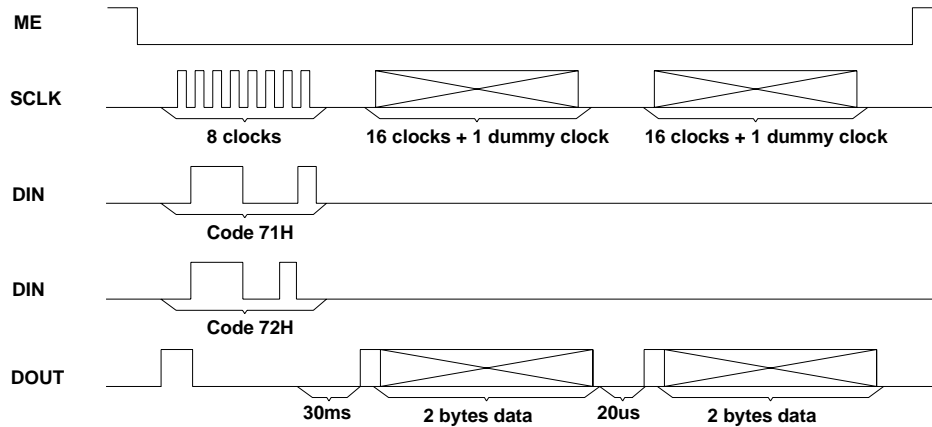
COMMUNICATION TEST



STORE PRESSURE WITH OFFSET

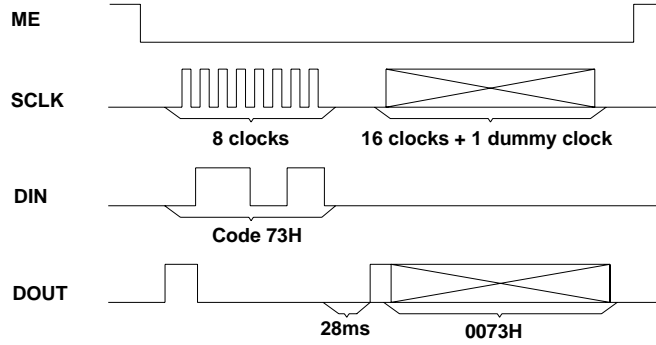


DEPTH OF SEA WATER

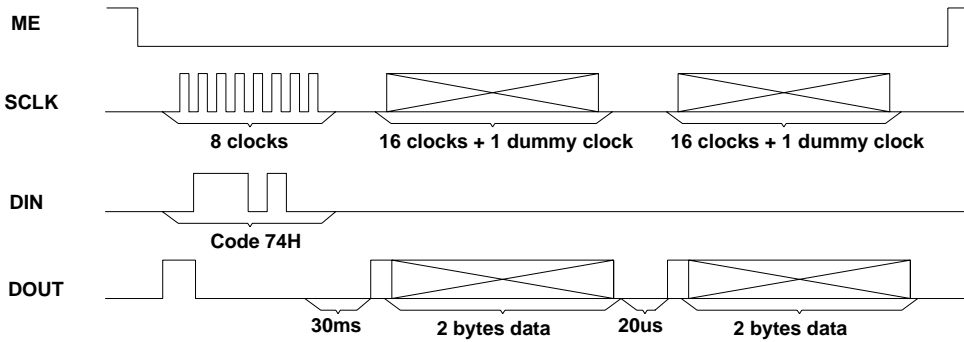




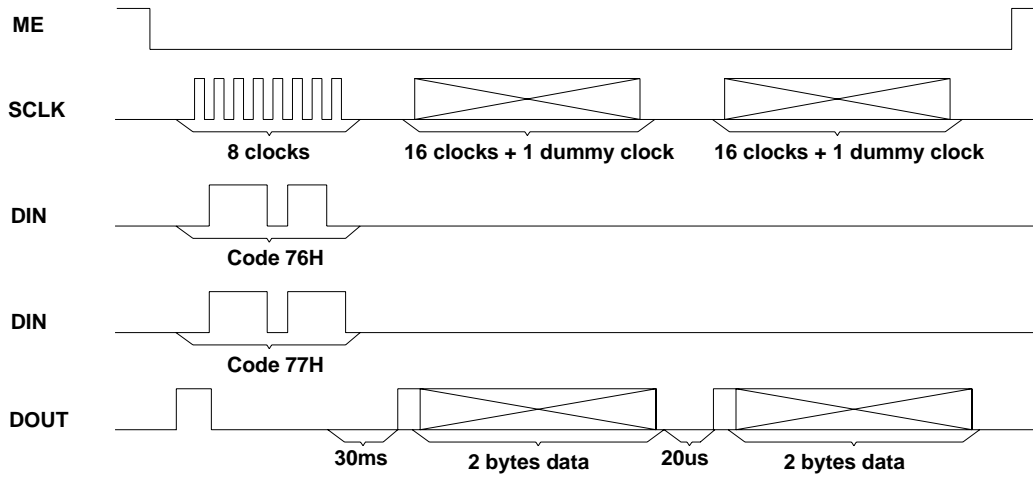
SET DEPTH 0m



DEPTH PRESSURE in mbar

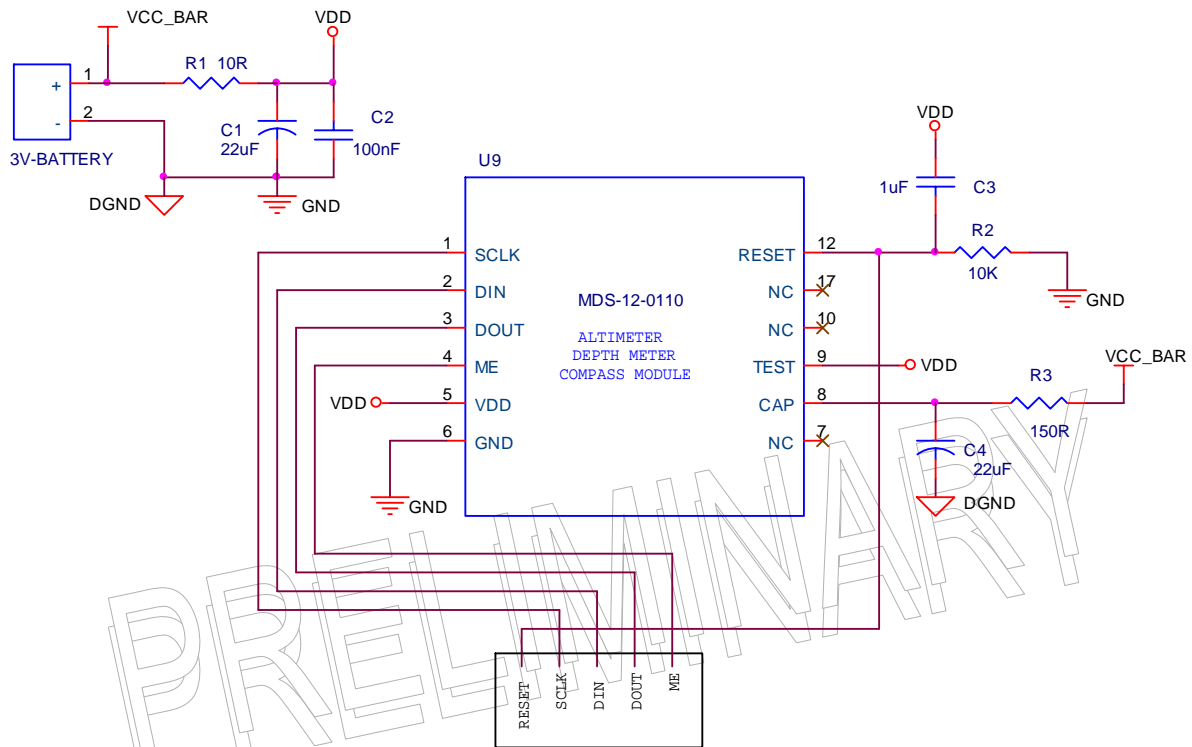


DEPTH OF LAKE WATER





Application schematic



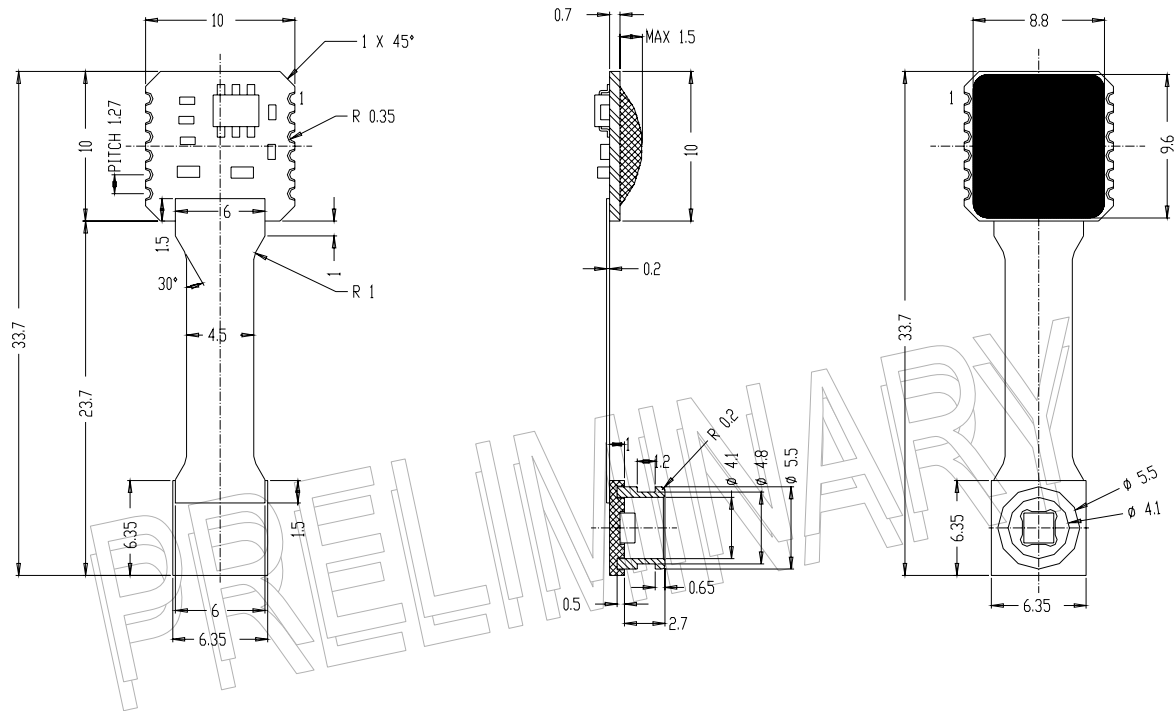
The application schematic of MDS-12-0110.

Important notice : Magnetic sensors placement

Place the magnetoresistive sensors such a way that their x or y axis passes through the center of the battery.



Physical size





ORDERING INFORMATION

PRODUCT CODE : MDS-12-0110

AGENT:

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List of updates:

1. Add sea/lake depth option.
2. Rev03: update company's address

PRELIMINARY